

§24    1 (b), 2 (b), 3, 4, 6

**Exercise 24.1)** In each case, determine whether the system  $A\vec{X} = \vec{b}$  is solvable and, if so, how many arbitrary variables will appear in the solution set.

b.)  $A = \begin{bmatrix} 1 & -1 & -1 & -1 \\ 1 & 1 & 2 & 1 \\ 2 & 0 & 3 & 2 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix}$

$$A^+ = \begin{bmatrix} 1 & -1 & -1 & -1 & 2 \\ 1 & 1 & 2 & 1 & 3 \\ 2 & 0 & 3 & 2 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & -1 & -1 & 2 \\ 0 & 2 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & -1 & -1 & 2 \\ 0 & 1 & 1/2 & 0 & 1/2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow$$

$$\begin{bmatrix} 1 & 0 & 3/2 & 1 & 5/2 \\ 0 & 1 & 1/2 & 0 & 1/2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = A_{row}^+, \text{ therefore } r(A^+) = 2$$

$$A = \begin{bmatrix} 1 & -1 & -1 & -1 \\ 1 & 1 & 2 & 1 \\ 2 & 0 & 3 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & -1 & -1 \\ 0 & 2 & 1 & 0 \\ 0 & 2 & 2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & -1 & -1 \\ 0 & 1 & 1/2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow$$

$$\begin{bmatrix} 1 & 0 & 3/2 & 1 \\ 0 & 1 & 1/2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = A_{row}, \text{ therefore } r(A) = 2$$

- ✓ Since:  $r(A) = 2 = r(A^+)$  it **IS SOLVABLE**,
- ✓ Arbitrary variables :  $\dim N(A) = n - r(A) = 4 - 2 = \underline{2}$

**Exercise 24.2)** In each case, solve the system  $A\vec{X} = \vec{b}$ , leaving your solution in the form of Theorem 24.4.

b.)  $A = \begin{bmatrix} 2 & 3 & -1 \\ 1 & 1 & 1 \\ 1 & 4 & -2 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 6 \\ 2 \\ 3 \end{bmatrix}$

$$A^+ = \begin{bmatrix} 2 & 3 & -1 & 6 \\ 1 & 1 & 1 & 2 \\ 1 & 4 & -2 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 1 & -3 & 2 \\ 1 & 1 & 1 & 2 \\ 0 & 3 & -3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 4 & 0 \\ 0 & 1 & -3 & 2 \\ 0 & 0 & 6 & -5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 4 & 0 \\ 0 & 1 & -3 & 2 \\ 0 & 0 & 1 & -5/6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 10/3 \\ 0 & 1 & 0 & -1/2 \\ 0 & 0 & 1 & -5/6 \end{bmatrix}$$

$$\vec{X} = \begin{bmatrix} 10/3 \\ -1/2 \\ -5/6 \end{bmatrix}$$

**Exercise 24.3)** Suppose  $\vec{X}$  and  $\vec{Y}$  are solutions of the non-homogeneous system  $A\vec{X} = \vec{b}$ . Show  $\vec{Z} = w_1\vec{X} + w_2\vec{Y}$  is a solution of  $A\vec{X} = \vec{b}$  if and only if  $w_1 + w_2 = 1$  (convex property).

(ANSWER IN BACK OF THE TEXTBOOK)

( $\Rightarrow$ ) Suppose  $\vec{Z} = w_1\vec{X} + w_2\vec{Y}$  is a solution of  $A\vec{Z} = \vec{b}$ .

Then  $\vec{b} = A\vec{Z} = A(w_1\vec{X} + w_2\vec{Y}) = w_1A\vec{X} + w_2A\vec{Y} = w_1\vec{b} + w_2\vec{b}$ .

Thus,  $\vec{b} = (w_1 + w_2)\vec{b} = \vec{0}$

Since  $\vec{b} \neq \vec{0}$  then  $w_1 + w_2 = 1$ .

( $\Leftarrow$ ) Suppose  $w_1 + w_2 = 1$

Then  $A\vec{Z} = A(w_1\vec{X} + w_2\vec{Y}) = w_1A\vec{X} + w_2A\vec{Y} = w_1\vec{b} + w_2\vec{b} = (w_1 + w_2)\vec{b} = 1\vec{b} = \vec{b}$ .

Thus,  $\vec{Z}$  is a solution.

**Exercise 24.4)** If  $\mathcal{S} \subset \mathcal{R}^m$  and  $\vec{X} \in \mathcal{R}^m$ , we will say that  $\vec{X}$  is orthogonal to  $\mathcal{S}$  (notation:  $\vec{X} \perp \mathcal{S}$ ) if  $\vec{X} \cdot \vec{Y} = 0$  for every  $\vec{Y}$  in  $\mathcal{S}$ . Further, for  $\mathcal{T} \subset \mathcal{R}^m$  we say  $\mathcal{T} \perp \mathcal{S}$  if  $\vec{X} \perp \mathcal{S}$  for all  $\vec{X}$  in  $\mathcal{T}$ . For all parts below, assume  $A$  is an  $m \times n$  matrix.

Before we address the questions, let look at these notes:

$E$  vector space  $E_1, E_2$ , subspace of  $E$

$E_1 \perp E_2$  is orthogonal if  $\vec{X}_1 \perp \vec{X}_2 = 0$  for all  $X_1 \in E_1$  and  $X_2 \in E_2$   $E_1 \cap E_2 = \{0\}$

$\vec{X} \in E_1 \cap E_2$   $\vec{X} = (X_1, \dots, X_2)$   $E_1 \perp E_2 \Leftrightarrow \vec{X}_1 \perp \vec{X}_2 = 0$

$$\sum_{k=1}^n X_k^2 = 0 \quad X_k = 0 \text{ for } k=1, \dots, n$$

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a.) Prove that if  $\vec{Y} \perp C(A)$ , then  $\vec{Y} \in N(A^T)$ .

Answer:  $A^T \vec{Y} = \vec{0}$  equivalent to  $\forall_i A_{ei} \cdot \vec{Y} = 0$

b.) Prove  $C(A) \perp N(A^T)$ .

Answer:  $\vec{X} \in C(A)$  and  $\vec{Y} \in N(A^T)$  (see answer (a) as the 1<sup>st</sup> half of this proof)

$$\vec{X} \cdot \vec{Y} = 0$$

c.) Use Exercise 22.13 to show that  $\dim N(A^T) + \dim C(A) = m$ .

Answer: Since  $\dim C(A) = \dim R(A)$  then  $\dim C(A^T)$

$$\text{Therefore} = \dim N(A^T) + \dim C(A) = m$$

d.) If  $B_1$  is a basis for  $C(A)$  and  $B_2$  is a basis for  $N(A^T)$ , prove  $B_1 \cup B_2$  is a basis for  $\mathcal{R}^m$ .

Answer: Show that  $B_1 \cup B_2$  is a basis for  $\mathfrak{R}^m$  will be  $\mathfrak{R}^m$  but also need to be Linearly Independent. (Look to answer (c) for part of the explanation).  $N(A^T) \perp C(A)$

e.) Prove that if  $\vec{X} \perp N(A^T)$ , then  $\vec{X} \in C(A)$ .

Answer:  $B_1$  is a basis for  $C(A)$       $B_1 = \{x_1, \dots, x_n\}$

$B_2$  is a basis for  $N(A^T)$       $B_2 = \{y_1, \dots, y_n\}$

$\vec{X} = \alpha x_1, \dots, \alpha x_n$       $B_1 Y_1 + \dots + B_k Y_k \neq 0$